#### TANGO Roadmap

### **Brainstorming Session**





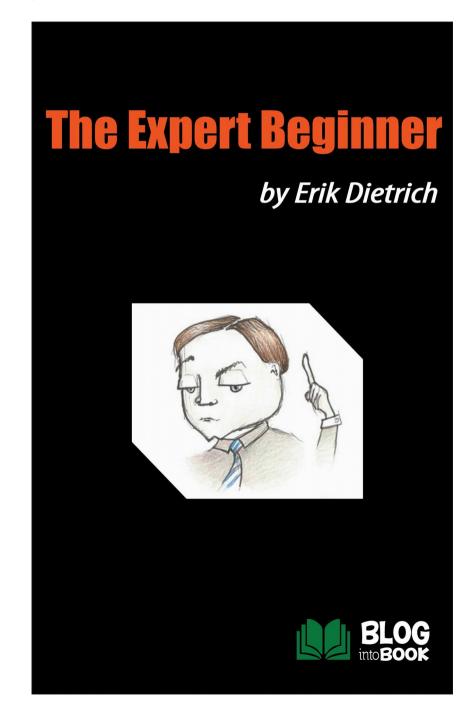
#### **Mission Statement**

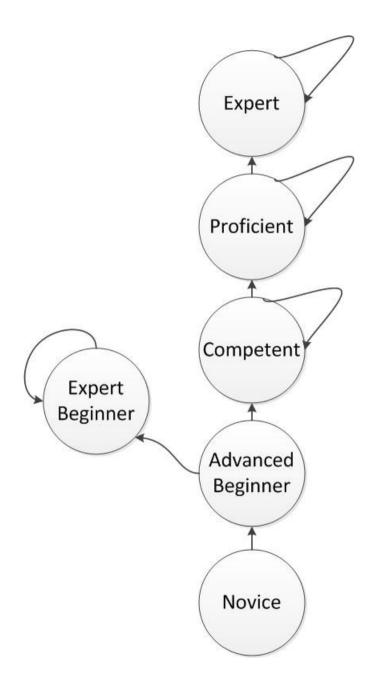
 Develop and provide an open source toolkit for building high performance and quality distributed controls systems for small and large installations.
 Work together with the community to ensure the toolkit stays modern, sustainable and serves the needs of large physics installations for at least the next 20 years. The long term goal is to become a de facto industrial standard

#### **Guiding Principles**



#### Why we need a Roadmap





#### Input to Roadmap

- RFC to mailing list :
  - 39 emails in 24 hours, thank you!
- H2020 project proposal from 2014
- Discussions with community
- Long term vision

#### RFC on mailing list

#### • Lajos:

- "the most important objectives for TANGO should be to increase the number of members of the community, and to go in the same direction as much as we can. To reach these things, I think we shouldn't start with coding new features; instead, we could improve the current things first. So, I think the three points below would really accelerate the things: refactoring documentation, packaging + automated installation, fixing bugs and improving code quality"

#### Thanks also to :

Benoit, Lorenzo, Frederic, Philippe, Wolfgang, Cristina, Igor, Jens,
 Sergi, Carlos, Zibi, ... and you!

#### Most requested features?



#### Most requested features

- Improve existing
  - Documentation
  - Code quality
  - Code sharing
- Move to GIT

Replace CORBA

- Title = Documentation
- **Description** = Improve the documentation, make it easier to navigate, read, more tutorials, control system designs
- Motivation = Make TANGO easier to learn for newbies, share knowledge about advanced features, design patterns
- Cost = constant effort of months to years
- Implementors = ELI-ALPS, ESRF, ...

#### RTFM? WABFM! Write a better manual



- **Title** = Move repository to git
- Description = Move the source code repository from SVN to git on SourceForge and GitHub
- Motivation = Enable better sharing and more contributors
- **Cost** = 3 6 months
- Implementers = ALBA, FRMII, ESRF, ...



- **Title** = Replace CORBA
- **Description** = Replace CORBA as synchronous communications protocol and remove all dependencies on CORBA (i.e. serialisation library, data types etc) with a pluggable protocol layer, use ZMQ as first implementation
- Motivation = Improve code base by refactoring, remove dependency on old protocol like CORBA which is not developed any more
- **Cost** = At least 2 years of development
- Implementors = Geoff Mant, Igor Khokhriakov, [ESRF, SOLEIL]

# CORBA is not the problem



- **Title** = Grow the Community
- Description = Continue to grow the community by expanding into new areas, introducing and accepting new members, publicising
- Motivation = Increase the resources and lifetime of TANGO
- Cost = constant effort of days and months
- Implementors = ALL

- Title = TANGO REST API
- Description = Define and implement a REST-API for TANGO for web applications
- Motivation = provide a simple way to access devices from the web and/or other clients
- Cost = 6 12 months
- Implementors = Igor Khokhriakov, MaxIV, ESRF, ...

- Title = TANGO Web application
- Description = Provide a generic web application for browsing and monitoring TANGO devices
- Motivation = Web is the ubiquitous user interface
- **Cost** = 6 12 months
- Implementors = Alessio Bogani, Igor Khokhriakov, ...

- **Title** = Security by encryption
- Description = Provide a secure way of accessing TANGO devices using a secure encrypted protocol
- Motivation = Secure access over public networks, protection from viruses on local area networks
- Cost = 6 12 months
- Implementors = ALBA, ELETTRA, Benoit Donnette, ...

- **Title** = Improve database schema
- Description = Change the database schema to fix the performance issues related to memorised attributes and other related problems.
- **Motivation** = Improve performance
- **Cost** = 3 6 months
- Implementors = SOLEIL, ELETTRA, ...

- **Title** = Improve device server sharing
- **Description** = Increase sharing of device servers
- Motivation = Improve quality
- **Cost** = 3 6 months
- Implementers = ESRF, ANKA, ELI-ALPS, ...

### Device server catalogue e.g. Eclipse Marketplace :

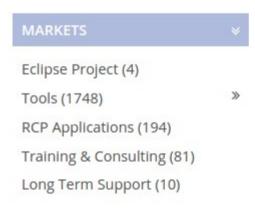


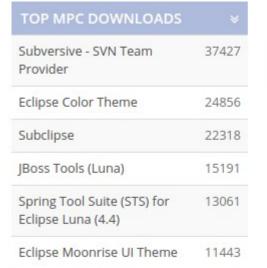
MY MARKETPLACE

ADD CONTENT

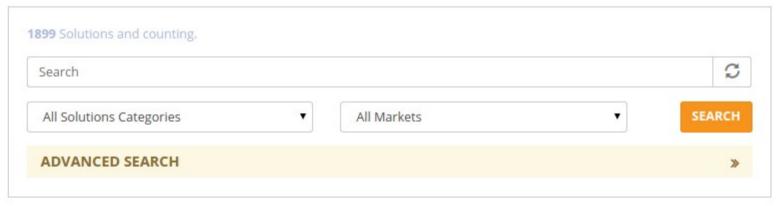
MORE\*

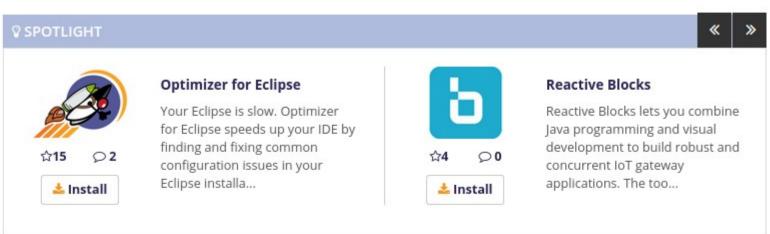
#### HOME / MARKETPLACE / NEW AND UPDATED SOLUTIONS





#### **14,031,757** solutions installed directly from Eclipse!





# Device server catalogue e.g. IntelliJ plugin repository:



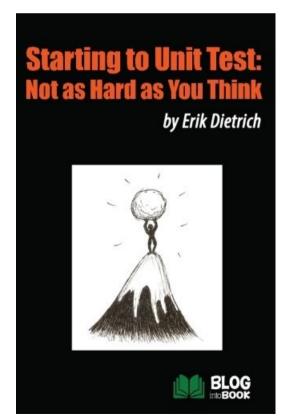
- **Title** = Long Term Support
- Description = Maintain an LTS version of TANGO which will be have bug fixes and patches for new major releases
- Motivation = Install new features without doing a major upgrade
- **Cost** = constant effort
- Implementers = ALBA, ...



- **Title** = Update Tango Virtual Box
- Description = Maintain and update the Tango Virtual Box to the have the latest version of Tango and all its tools
- Motivation = Provide an easy way to try out Tango
- **Cost** = constant effort
- Implementers = Raphael Ponsard, ESRF, ...



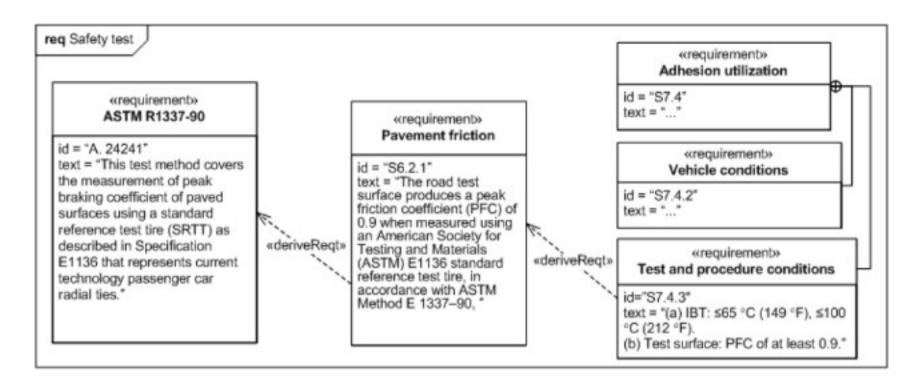
- **Title** = Generate Unit Tests automatically
- Description = Pogo to Generate Unit Test for Device Servers in Python, C++ and Java
- Motivation = Improve code quality with TDD
- **Cost** = 6 months
- Implementers = MaxIV, Nexeya, ESRF, ...



- **Title** = Interface SysML tools
- Description = Interface SysML to TANGO so that it can be used a language for specifying device servers
- Motivation = Improved specification of device interfaces
- **Cost** = 12 months
- Implementers = INAF, SKA, ...

# SysML Requirements Specification





http://formalmind.com/en/blog/requirements-uml-sysml

- Title = Remove Boost.Python from PyTango
- Description = Replace Boost as the interoperable layer between PyTango and the C++ Tango kernel
- **Motivation** = fix some old bugs, make PyTango easier to maintain, Boost not actively developed any more
- Cost = 6 12 months
- Implementors = ESRF, ...

#### Where to find resources?

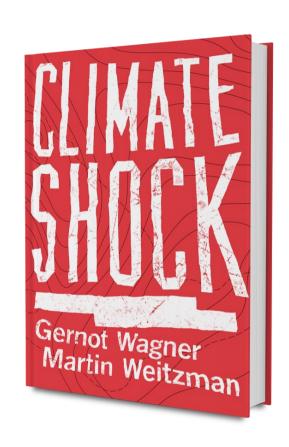
- First and foremost the community!
- Collaboration Contract (< 100 k€ / year)</li>
- Google Summer of Code
- EU H2020 projects







#### Do not free ride!



#### **Proposal for Roadmap**



Database Schema Replace CORBA

**Unit Tests Generation** 

SysML tools

**Fast Archiver** 

Git

**Encryption** 

**REST api** 

Web app

**Documentation** 

**Packaging** 

**V9** 

**Virtual Box** 

**LTS** 

**V10** 

2015 2016 2017 2018 2019 2020

**Evolution** 

#### Conclusion

- Roadmap converges
- Next steps:
  - 1)Publish roadmap
  - 2)Community feedback
  - 3) Submit to Executive Committee
  - 4) Find resources community, collaboration contract, ...
  - 5)Plan Who will implement What When

## Dziękuję Solaris!

Thank you Piotr

+

the team!